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Universal inverse design of 2D nematic elastomers

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Abstract:

Thin nematic elastomer sheets can be programmed, via the nematic director field embedded into them, to take different shapes in different environments. Recent experiments from various groups demonstrate excellent control over the director field, thus opening a door for achieving accurate and versatile designs of shapeshifting surfaces. At the crux of any effort to implement this design mechanism lies the inverse design problem—given an arbitrary surface geometry, constructing the director field that would induce it upon actuation. In this talk, I describe several aspects of this inverse problem. I present a numerical algorithm for finding approximate global solutions to the inverse problem for any 2D geometry. I show analytically the existence of many local solutions for any smooth geometry, provide an algorithm for their integration, and show a convenient classification useful for finding optimized director fields for a given surface geometry. I further discuss nonsmooth surface geometries, and how these can be realized via topological defects and domain walls in the nematic director field.

> Date & Location: Monday, May 11, 2021, 11:00